

Denis Hadjivelichkov

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| Education | |
|---|----------------|
| University College London (United Kingdom), PhD at the CDT for Foundational Artificial Intelligence, Topics: Imitation Learning and Self-Supervised Learning for Robotics Part of the Robot Perception and Learning Lab led by Dr. Dimitrios Kanoulas | 2020 – Present |
| University College London (United Kingdom), MSc Robotics and Computation – 1st Class Distinction Topics: Robotics, Machine Learning, Graphical Models, Multi-Agent RL | 2019 – 2020 |
| University of Manchester (United Kingdom), BEng Mechatronic Engineering with Industrial Experience – Grade: 82%, 1st Class Topics: Robotics, Mechanics, Electronics, Control Systems, Mathematics | 2015 – 2019 |
| Work Experience | |
| Teaching Assistant, UCL <ul style="list-style-type: none">Assisted in teaching for MSc module Robot Sensing, Interaction and ManipulationAssisted in curriculum creation, student supervision and assessment | 2020 – Present |
| Design and Verification Engineer (Image and Vision), Arm <ul style="list-style-type: none">Designed and verified image processor modules in SystemVerilog.Performed optimization, synthesis and linting of hardware code.Work was successfully integrated into marketed products | 2017 – 2018 |
| Summer Intern for Computer Vision, University of Manchester <ul style="list-style-type: none">Implemented face detection and recognition methods (Eigenface, Fisherface, LBP)Developed a mobile video face recognition system on a RaspberryPiIntegrated the system with a speech recognition module | 2016 – 2016 |
| Research Experience | |
| MSc Dissertation Whole-body Control of a Mobile Manipulator using Reinforcement Learning <ul style="list-style-type: none">Trained a mobile manipulator to avoid obstacles and reach goalUsed state-of-the-art agent and explored several directions of improvementAchieved a 24% higher success rate than the baseline. | 2019 – 2020 |
| BEng Dissertation, Localization of Weeds in Aerial Images <ul style="list-style-type: none">Developed a model combining image processing and supervised learning to detect a particular species of carcinogenic weeds in aerial images.Dealt with the problem of limited data and viewpoint mismatch.Achieved a high final recall rate. | 2018 – 2019 |

| Projects and Awards | |
|---|-------------|
| Embedded Systems Project , University of Manchester <ul style="list-style-type: none"> Designed and developed an autonomous buggy that navigates and overcomes obstacles using PID control. Won the Prize for Best Software Documentation. | 2016 – 2017 |
| Second Place for the project AskNigel, Student Hack IV (Manchester) <ul style="list-style-type: none"> Within 24 hours as part of a team, developed an animatronic assistant that answers spoken questions and provides local recommendations Integrated with several commercial APIs | 2016 |

| Volunteering | |
|---|-------------|
| Robogals Manchester Volunteering Society – Marketing Manager <ul style="list-style-type: none"> Led and promoted basic robot programming workshops for young girls Ensured that the workshops were engaging and useful | 2016 – 2017 |
| University of Manchester – PASS Leader <ul style="list-style-type: none"> Assisted new students with their studies and their orientation at university Achieved the certificate for highest turnout | 2016 – 2017 |

| Skills | |
|------------------------------|---|
| Programming Languages | Strong command of Python, C++, MATLAB , SystemVerilog. Fair command of Perl, MySQL, LabVIEW, HTML |
| Machine Learning | Strong command of common packages (PyTorch, openCV, Tensorflow, PyBullet) Worked extensively with learning models spanning reinforcement learning, self-supervised learning, computer vision. |
| Robotics | Strong command of Robot Operating System (ROS) , Gazebo, Eigen, PCL, KDL Deep understanding of kinematics, dynamics and control systems. |
| Computer Vision | Strong command of various computer vision methods for recognition, detection, dimensionality reduction (Viola-Jones, Eigenface, PCA, CNNs) |
| Other Technical | Worked with version control (git, svn). Experienced with concurrent systems , High Performance Computing. |
| Soft Skills | Extensive experience with both collaborative and independent work, taking accountability over my own product and effective time management. |

| Languages | |
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| Bulgarian | Native language |
| English | Fluent, (C2 Proficient) Certificate for Advanced English – A |
| German | Fluent, (C2 – Proficient) Test für Deutsch als Fremdsprache – 5,5,5,4 |

References available upon request.